

The Bootstrap (EH, Chapters 10 and 11)

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Background: Standard Errors

A basic idea in frequentist statistics is the *standard error*.

Given a “sample of data” x , we seek to estimate some unknown quantity θ .

Let $\hat{\theta} = s(x)$ denote our estimate from the sample x .

We understand that our sample as given imperfect information information so we seek a standard error \hat{se} (which is also a function of x) such that

$$P(\theta \in \hat{\theta} \pm k_{\alpha} \hat{se}) = 1 - \alpha$$

The interval,

$$(\hat{\theta} - k_{\alpha} \hat{se}, \hat{\theta} + k_{\alpha} \hat{se})$$

is called a *confidence interval*, which coverage probability $(1 - \alpha)$.

The classic example is estimation of a mean.

If $s = \{X_1, X_2, \dots, X_n\}$ is our sample where the X_i are iid from some distribution and $\theta = E(X)$.

Our estimator is $\hat{\theta} = \bar{X}$.

We let,

$$s^2 = \frac{1}{n-1} \sum (X_i - \bar{X}), \quad \hat{se} = \frac{s}{\sqrt{n}}.$$

Then, for large enough n ,

$$P(\theta \in \bar{X} \pm 1.96 \hat{se}) \approx .95$$

About 95% of the time, the true value will be in the interval!

Let $\text{Var}(X) = E((X - \mu)^2) = \sigma^2$.

This result relies on some key assumptions

- ▶ The X_i are iid.
- ▶ $\bar{X} \approx N(\mu, \frac{\sigma^2}{n})$
- ▶ $\text{Var}(\bar{X})$ has the simple form σ^2/n .
- ▶ In large samples we can *plug-in* s^2 in place of σ^2 .

How can we obtain standard errors and confidence intervals for estimators more complex than \bar{X} ?

EH:

“Direct standard error formulas exist for various forms of averaging such as linear regression, and for hardly anything else.” (page 155)

The goal of the *Jackknife* and the *bootstrap* is to compute standard errors, or, more generally, confidence intervals for complex estimators (e.g. not averages) without making many assumptions.

And, to do it in a computationally feasible way.

Example

Suppose you have the simple linear regression model and you want an interval for

$$E(Y | x) = \beta_0 + \beta_1 x$$

Easy!!

Example

Suppose you have a simple logistic regression model with one x and you want an interval for

$$P(Y = 1 | x) = F(\beta_0 + \beta_1 x); \quad F(\eta) = \frac{e^\eta}{1 + e^\eta}$$

Not so easy.

Delta method??

The Jackknife Estimate of Standard Error

Suppose we have

$$x_i \sim F, \text{ iid}, \quad i = 1, 2, \dots, n.$$

The x can belong to an set.

Let $x = (x_1, x_2, \dots, x_n)$ and,

$$\hat{\theta} = s(x).$$

Note that s could be a complex algorithm, rather than a simple function.

We want to compute the standard error, that is, we want to estimate the standard deviation of $\hat{\theta} = s(x)$.

Let,

$$x_{(i)} = (x_1, x_2, \dots, x_{i-1}, x_{i+1}, \dots, x_n)$$

and,

$$\hat{\theta}_{(i)} = s(x_{(i)}).$$

Then the jackknife estimate of the standard error for $\hat{\theta}$ is

$$\hat{s}_{\text{jack}} = \left[\frac{n-1}{n} \sum_{i=1}^n (\hat{\theta}_{(i)} - \hat{\theta}_{(\cdot)})^2 \right]^{1/2}, \text{ with } \hat{\theta}_{(\cdot)} = \frac{1}{n} \sum_{i=1}^n \hat{\theta}_{(i)}$$

The “fudge factor” $\frac{n-1}{n}$ is chosen to make \hat{s}_{jack} the same as the classic formula for $\hat{\theta} = \bar{X}$.

Note

- ▶ intuitive that $(\hat{\theta}_{(i)} - \hat{\theta}_{(\cdot)})$ captures sample variation in the estimator.
- ▶ fudge factor gets the scaling right.
- ▶ It is nonparametric, no special form for F need by assumed.
- ▶ It is automatic. Just need code for $s(x)$, then the same simple code works for everything.
- ▶ $\hat{s}e_{\text{jack}}$ is upwardly biased.

Example:

Standard error of a correlation.

The Nonparametric Bootstrap

The standard error is the a measure of the variation we would observe if we repeatedly sampled x from F and computed $s(x)$ for each draw of x .

This is impossible since F is unknown.

Instead the bootstrap substitutes an estimate \hat{F} for F , and then estimates the frequentist standard error by direct simulation.

That is:

- ▶ draw x repeatedly from \hat{F} .
- ▶ for each x draw, compute $s(x)$.
- ▶ compute the sample standard deviation of the draws.

For formalize this, we need the notion of a *bootstrap sample*.

Given observed (x_1, x_2, \dots, x_n) let a bootstrap sample

$$x^* = (x_1^*, x_2^*, \dots, x_n^*)$$

where each x_i^* is drawn with equal probability *and replacement* from $\{x_1, x_2, \dots, x_n\}$.

From each bootstrap sample we compute

$$\hat{\theta}^* = s(x^*).$$

We then draw B bootstrap samples x^{*b} , $b = 1, 2, \dots, B$.

At each bootstrap sample we compute $\hat{\theta}$:

$$\hat{\theta}^{*b} = s(x^{*b}), \quad b = 1, 2, \dots, B.$$

We then have:

$$\hat{s}e_{\text{boot}} = \left[\frac{1}{B-1} \sum_{b=1}^B (\hat{\theta}^{*b} - \hat{\theta}^{*\cdot})^2 \right]^{1/2}, \quad \text{with } \hat{\theta}^{*\cdot} = \frac{1}{B} \sum_{b=1}^B \hat{\theta}^{*b}$$

We can use the bootstrap as *plugging in* the empirical distribution!!

Our model is

$$F \xrightarrow{iid} x \xrightarrow{s} \hat{\theta}.$$

In principle we would draw x repeatedly and observe the variation in $\hat{\theta}$.

Since we can't do this (don't know F) we *plug-in* an estimate

$$\hat{F} = \sum_{i=1}^n \frac{1}{n} \delta_{x_i},$$

where δ_x puts probability 1 on x .

\hat{F} is simply the empirical distribution.

Plugging-in means we replace

$$F \xrightarrow{iid} x \xrightarrow{s} \hat{\theta}.$$

with,

$$\hat{F} \xrightarrow{iid} x^* \xrightarrow{s} \hat{\theta}^*.$$

We only get one $\hat{\theta}$, but we get $\hat{\theta}^{*b}$, $b = 1, 2, \dots, B$, and we choose B .

Note, Jackknife and Bootstrap

- ▶ completely automatic. Input x and s , get out $\hat{s}e_{\text{boot}}$.
- ▶ Bootstrapping *shakes* the original data more violently than the jackknife.
- ▶ There is nothing special about standard errors, we could bootstrap to estimate $E(|\hat{\theta} - \theta|)$.
- ▶ The jackknife method is more conservative than the bootstrap method, that is, its estimated standard error tends to be slightly larger.
- ▶ Jackknife performs poorly when the estimator is not sufficiently smooth, i.e., a non-smooth statistic for which the jackknife performs poorly is the median.
- ▶ bootstrap can be more computationally demanding.

Bootstrap Confidence Intervals

Why did we want to estimate the se ?

We want to have some way of gauging the uncertainty associated with our estimation of θ given the amount of information in the sample x .

Can we use the bootstrap to construct confidence intervals?

The obvious thing to try is the *standard interval*

$$\hat{\theta} \pm 1.96 \hat{se}.$$

This interval is useful but may be inaccurate if the sampling distribution of $\hat{\theta}$ is not normal.

Typically we use Central Limit Theorem ideas to argue that $\hat{\theta}$ will be normal in “large samples” but the sample may not be large enough.

In particular the interval $\hat{\theta} \pm 1.96 \hat{s}\hat{e}$ is always symmetric around $\hat{\theta}$ and that may not be appropriate if the sampling distribution of $\hat{\theta}$ is skewed.

There are a variety of ways to get confidence intervals from the bootstrap that perform better than the standard interval and we will just look at one simple approach, *the percentile method*.

The Percentile Method

The goal is to automate the computation of confidence intervals using the bootstrap distribution of the estimator $\hat{\theta}$.

The percentile method uses the shape of the bootstrap empirical distribution of the

$$\hat{\theta}^{*1}, \hat{\theta}^{*2}, \dots, \hat{\theta}^{*B}$$

Let, \hat{G} be the empirical CDF of the $\hat{\theta}^{*b}$, so that $\hat{G}(t)$ is the proportion of $\hat{\theta}^{*b}$ less than t

$$\hat{G}(t) = \#\{\hat{\theta}^{*b} \leq t\}/B.$$

Then the α th percentage point $\hat{\theta}^{*(\alpha)}$ given by the inverse function of \hat{G} ,

$$\hat{\theta}^{*(\alpha)} = \hat{G}^{-1}(\alpha).$$

So, $\hat{\theta}^{*(\alpha)}$ is the value putting proportion α of the bootstrap sample $\hat{\theta}^{*b}$ to its left.

$$\hat{\theta}^{*(\alpha)} = \hat{G}^{-1}(\alpha).$$

Then, for example, the 95% central percentile interval is

$$(\hat{\theta}^{*(.025)}, \hat{\theta}^{*(.975)})$$

Notes:

- ▶ the method requires bootstrap samples on the order of $B = 2000$.
- ▶ the argument for the method centers around the fact that it is invariant to monotonic transformations of θ .
- ▶ two further improvements are “BC” and “BCa”, where BC stands for *bias corrected* are covered in EH 11.3.

The Parametric Bootstrap

The nonparametric bootstrap can be described as:

$$\hat{F} \xrightarrow{iid} x^* \xrightarrow{s} \hat{\theta}^*.$$

where \hat{F} is the empirical distribution.

The empirical distribution is appealing because it is nonparametric.

But, if we have a parametric family that we believe in or simply want to explore, we can get \hat{F} from our parametric estimation.

Suppose $f(x | \mu)$ is a parametric family.

Now suppose we have an estimate $\hat{\mu}$ (e.g. the mle), then we can simply replace the empirical distribution with $f(x | \hat{\mu})$:

$$f(x | \hat{\mu}) \rightarrow x^* \rightarrow \hat{\theta}^*.$$

and get a bootstrap distribution estimate \hat{se}_{boot} as before.

As before, we could bootstrap to get any quantity of interest (not just the an se).

Basic Example

Suppose $x = (x_1, x_2, \dots, x_n)$ are a sample assumed to be iid $N(\mu, 1)$.

Then $\hat{\mu} = \bar{x}$ and a parametric bootstrap sample is

$$x^* = (x_1^*, x_2^*, \dots, x_n^*), \quad x_i^* \stackrel{iid}{\sim} N(\bar{x}, 1)$$

Not So Basic Example

Suppose we have

$$x_i = \alpha + \beta x_{i-1} + \epsilon_i, \quad \epsilon_i \sim N(0, \sigma^2).$$

Given an estimate $(\hat{\alpha}, \hat{\beta}, \hat{\sigma})$, we can draw bootstrap samples

$$x_i^* = \hat{\alpha} + \hat{\beta} x_{i-1}^* + \epsilon_i, \quad \epsilon_i \sim N(0, \hat{\sigma}^2), \quad i = 2, 3, \dots, n.$$

Then we could, for example, get estimates of (α, β, σ) from each bootstrap sample.

Note:

For time series data there is a *Moving Blocks Bootstrap* (EH 10.3) but it seems tricky.

For more complex non iid models, the parametric bootstrap seems like just a great idea.

Perhaps more generally, we often want to test a complex modeling approach (model + computation).

Often we try it on simulated data and real data.

But, we never are sure the simulate data represent a good “use case” and we never know the truth with the real data.

Simulating data from a model fit to data seems like an approach worth thinking about in general.